

Concept Design Review



NASA Lunabotics Competition Team 15: Hexcavator

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The Issue

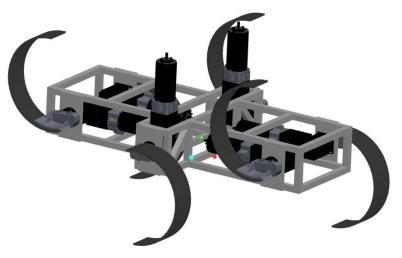
- Moon has un-mined resources
- Resources give insight on moon settlement
- Difficulty involved with excavating remotely

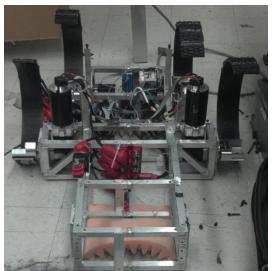




The Task

- Last year
- Capable of excavation
- Controlled via WiFi
- Limited size
- Handles an environment with obstacles



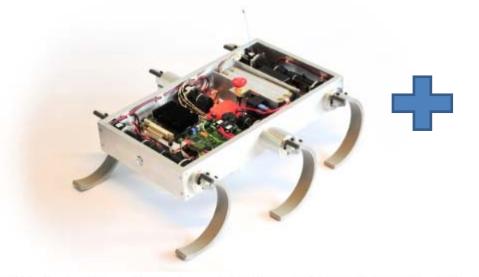




The Solution

- Hexapedal robot
 - RHex family
- Attach excavation system









Excavators

- Compact/Mini Excavator
- Dragline Excavator
- Long Reach Excavator





Compact Excavator

- Definition
- Pros
- Cons





Dragline Excavator

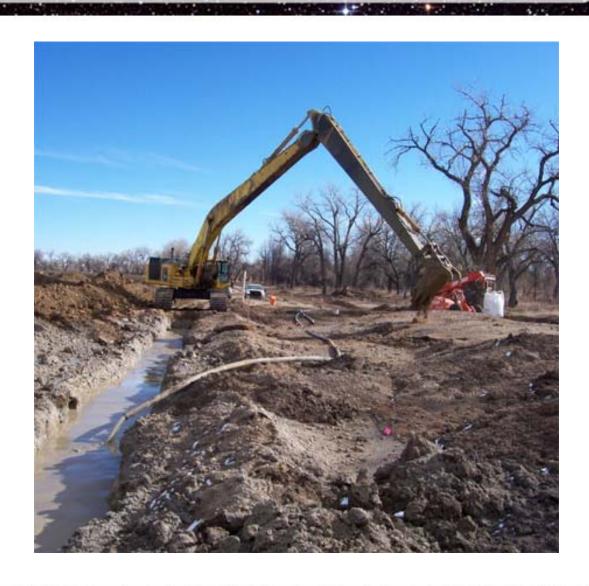
- Definition
- Pros
- Cons





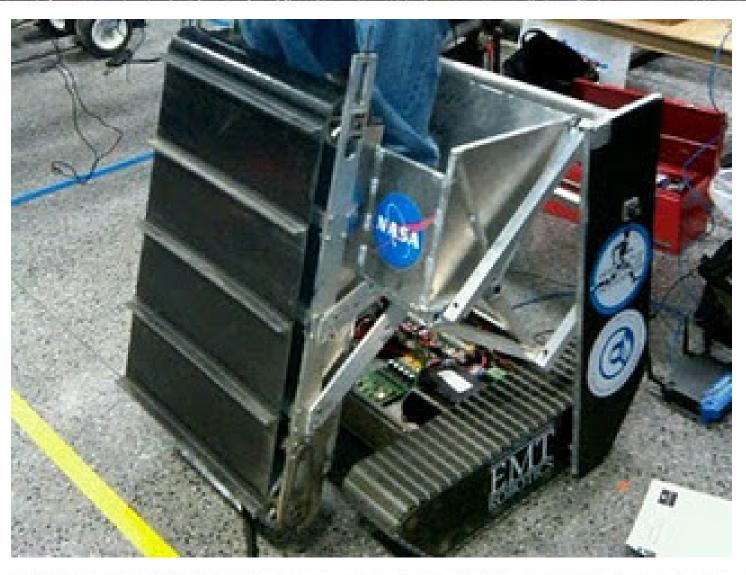
Long Reach Excavator

- Definition
- Pros
- Cons





Artemis FSU Lunabot





MSU Lunabot 2010



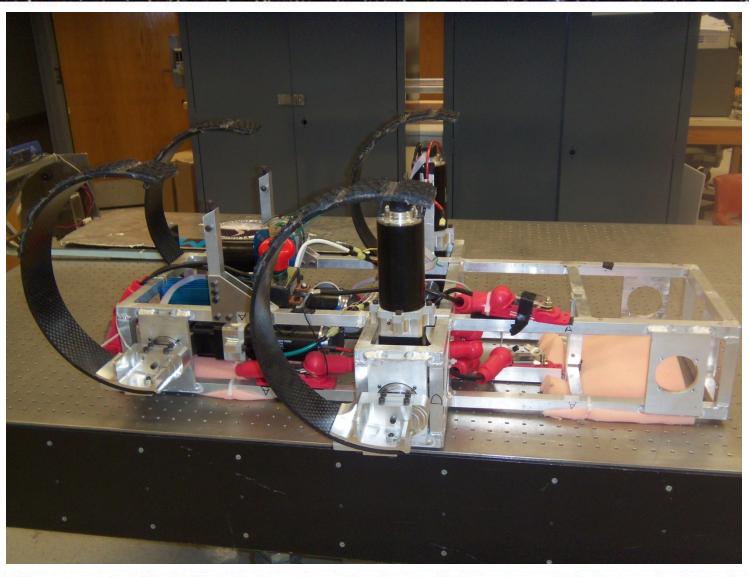


Laurentian University Lunabot 2011



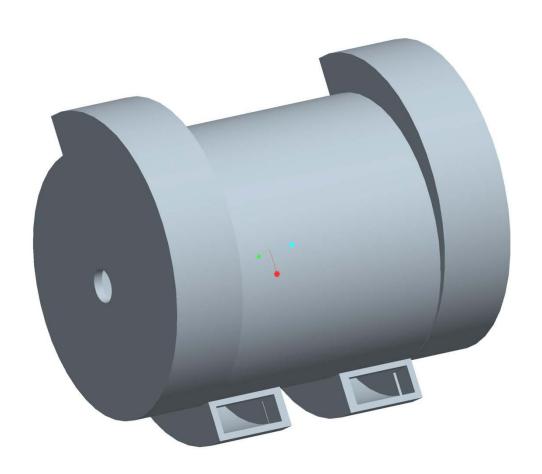


Hexcavator



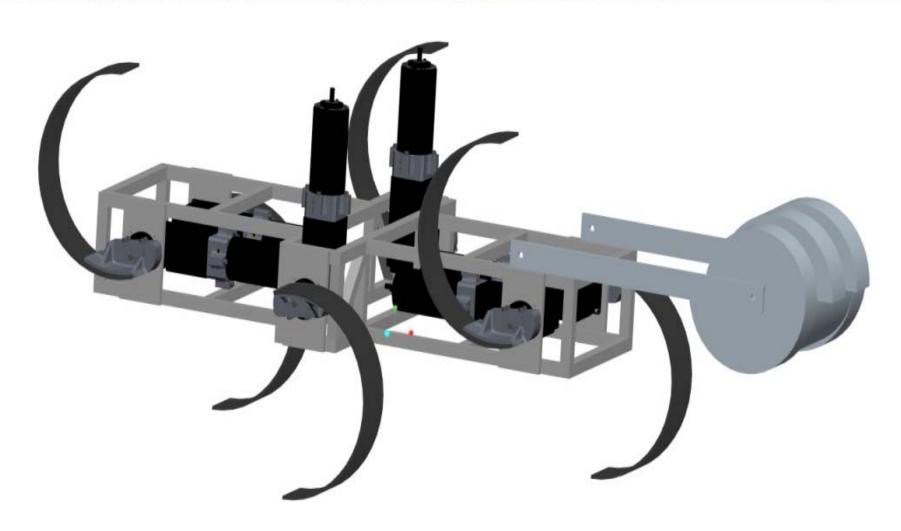


Design 1: Excavation Drum



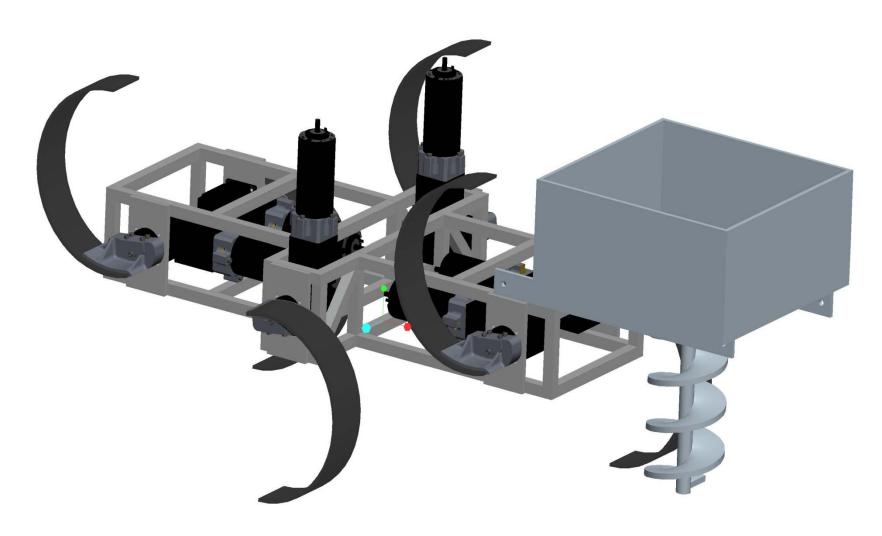


Design 1: Excavation Drum



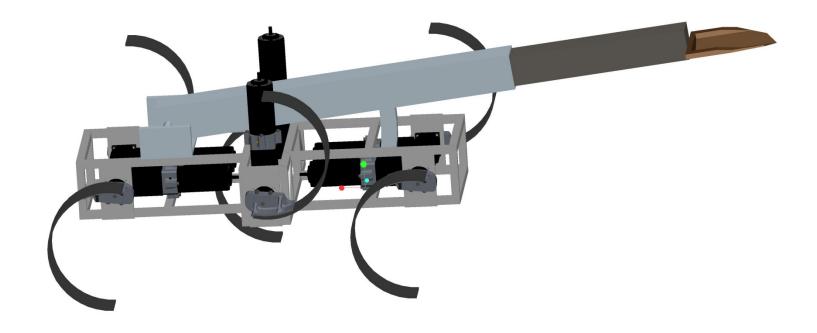


Design 2: Auger





Design 3: Shovel and "Screw Jack"





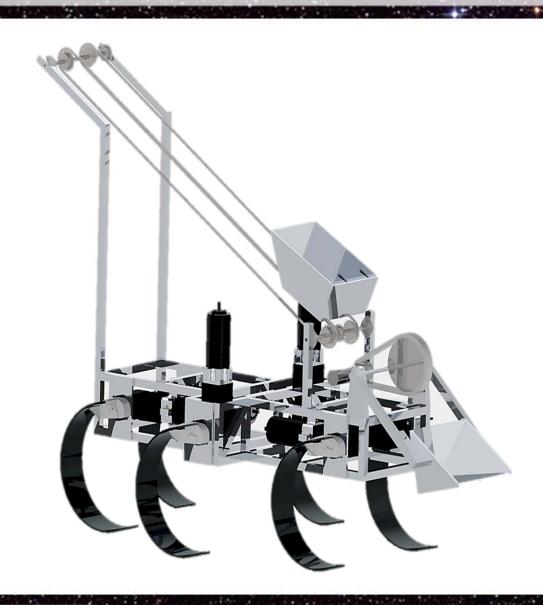
Design 3: Mechanism

- Arm Fixture
- Shovel Head
- Motor System
- "Screw Jack" Actuation
- Hexcavator Mount
- Raising Arm
 - Motor Actuator





Design 4: Shovel and Dump Bucket





Questions?









Works Cited

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